

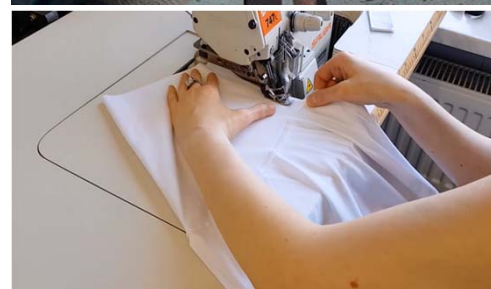


CoLab

R&D on robot controlling using visual servo and machine learning

Our system uses machine learning to recognize the position and state of the target object from visual and tactile information, and automates tasks that require real-time feedback with a robot.

We are currently conducting demonstration experiments in fields considered difficult to automate using robots, such as surface polishing and cloth handling, and are looking for joint research partners, interns, and parts suppliers.



AIRBIC, Room A06, Manufacturing